

HOW KALMAR MUNICIPALITY CREATED A DIGITAL TWIN OF A LANDMARK, TWELFTH-CENTURY CASTLE.

Kalmar Municipality Streamlines Digital Capture for Community Planning



Background

In December 2019, the municipal government of Kalmar, Sweden, embarked on an EU-funded StreamSam initiative to digitize its community development process. The [StreamSam](#) project is creating a 3D digital model of historic Kalmar municipality and the surrounding environment from point cloud data of buildings and terrain. Having access to this resource is expected to improve the development planning and public engagement processes. In Kalmar, the StreamSam project commenced with the



digitization of the region's best known landmark: Kalmar Castle.

Challenge: Capturing a Heritage Landmark Completely and Quickly

One of Sweden's grandest and most well-preserved medieval fortresses, Kalmar Castle, sprawls across 2.5 hectares (6.3 acres) and includes turrets, a moat, and a drawbridge. Its size and complex structure made it a challenging project, especially in capturing exposed areas, such as roofs.



Initially, the Kalmar municipal engineering team intended to capture data of the castle with a terrestrial laser scanner, but they found the process slow and the results incomplete. Obtaining data of the castle roof was not possible using traditional tools and methods.

Kalmar's StreamSam programme team sought a means of capturing detailed, accurate point cloud data of the entire castle complex quickly, economically, and safely.

AMKVO CEO Alex Paulusson scanning Kalmar Castle with Hovermap.

Solution: Send in Hovermap

In April 2020, the Kalmar StreamSam team contacted geodata and remote sensing specialist AMKVO to demonstrate [Hovermap](#). AMKVO subsequently conducted a trial to evaluate Hovermap's performance against that of a traditional terrestrial scanner. The comparison assessed capture coverage, time spent on capture, and accuracy.

"The versatility of being able to switch from ground to aerial scanning is a big win for our survey team. Having this technology will allow us to accelerate the progress of the StreamSam project."

Simon Vestlund, project manager, StreamSam

AMKVO used a drone-mounted [Hovermap](#) to carry out four 15-minute flights to scan the roof and courtyard of the castle and each of its four sides. AMKVO then completed two 15-minute walking scans to capture the interior of the historic site.

Scanning two sides of the castle using a Trimble SX-10 total station took 10 hours. AMKVO estimated that completing a scan of the entire castle site using this method would take more than two days.

[Hovermap](#) was able to completely scan the Kalmar Castle and provide a consistent level of accuracy across the project site, whereas the Trimble SX-10 was unable to capture the complex interior areas and the roof.

Ground control was established with 21 Ground Control Points (GPSs) set up across the site. [Hovermap](#) returned an absolute accuracy of 40mm, which is sufficient for Kalmar's digital twin and GIS applications.

"We couldn't afford to be tied to the ground with stationary measuring instruments. With a drone-mounted Hovermap, we could cover ground quickly and scan the entire castle, including the roof. As a result, we were able to increase productivity by between 50 and 90%."

Simon Vestlund, project manager, StreamSam

Deliverables

Point cloud data of the castle captured by [Hovermap](#) took three hours to process and merge using Emesent software. Files in .laz format were uploaded to CloudCompare for visualization and analysis.

By comparison, data captured using the Trimble SX-10 took 10 hours to process.

Obtaining Comprehensive Building Data Quickly and Safely

Using [Hovermap](#) enabled the Kalmar StreamSam team to collect and process comprehensive and detailed data of the castle within hours rather than days.

The data set was imported into CAD software to create a 3D digital model

Hovermap flew four 15-minute data capture missions, capturing exterior walls and roofs

"The Hovermap met our accuracy objectives by achieving absolute accuracy of 40 mm, based on 10 control points evenly distributed across the 2.5 ha site. This is an impressive outcome for

a SLAM scanner and more than sufficient for the Kalmar municipality 3D models."

AMKVO CEO Alex Paulusson

AMKVO established 21 ground control points across the 2.5 ha site to maintain scan accuracy.

Point cloud data captured by [Hovermap](#) can be imported directly into Kalmar's software platforms, including Trimble Business Center and Esri ArcGIS. From these, it can be used to create 3D building models and digital terrain and elevation models. Data can also be used to inform flood maps, earthworks calculations, solar radiation, and shadow analysis.

Kalmar has purchased a [Hovermap](#) scanner for the StreamSam team to use on the project. Using [Hovermap](#) instead of terrestrial equipment has reduced time spent on site by between 50 and 90%.

Using [Hovermap](#) helps the Kalmar StreamSam team collect large amounts of data in short sessions. "It's incredibly easy to start scanning with [Hovermap](#). We can arrive at a site, unpack, and press start. We're scanning in minutes," says Simon Vestlund, StreamSam project manager. "With the simultaneous localization and mapping (SLAM) technology,

we don't need to worry about GPS. We can scan indoors and outdoors, with and without the drone. The scan accuracy is very good for our 3D modelling and the solution is affordable."

□ A 3D digital model of Kalmar Castle, created using Hovermap data imported into CAD software. Image source: streamsam.kalmar.se.

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□ **The Hovermap colorized point cloud digital twin of Kalmar Castle was produced by merging six scans.**

<https://www.gim-international.com/case-study/kalmar-municipality-streamlines-digital-capture-for-community-planning>
