

MoLaS: Mobile Laser Scanning Technology Workshop



The collection of 3D data from moving platforms such as vehicles or aircraft is one of the most interesting challenges in the area of object detection and reconstruction. Laser scanners, which collect data rapidly, reliably and with high precision, play a key role in this context. High-precision systems, calibration and referencing are therefore the central aspects of current research activities and applications. From 23-24 November 2016, Fraunhofer IPM is hosting the second international MoLaS workshop on the subject of mobile laser scanning at its premises in Freiburg, Germany.

The first MoLaS workshop in 2014 with 120 participants has shown that there is a growing interest in discussing technological aspects of mobile laser scanning. This year's workshop will focus on state-of-the-art and future technological trends in mobile laser scanning and is aimed at scientists, service providers, manufacturers and users of the technology.

Thirteen internationally renowned experts in 3D mapping with mobile laser scanning systems will present current trends in research and development in the field of:

- Sensors
- Calibration
- Data interpretation & Visualisation
- Application

This year the program includes keynotes by Google and IAV GmbH. An exhibition and a poster session are part of the event. The workshop will be held in English.

For more information and registration visit www.molas-workshop.org.

<https://www.gim-international.com/content/news/molas-mobile-laser-scanning-technology-workshop>
