

The system will be like a cyber co-pilot that supports navigation of ground vehicles by using artificial intelligence and

The project award is for four years, with two years awarded now and a two-year option for the Army Research Lab to continue funding the

work.



This image shows the concept of a smart, computer vision-based navigation system using multi-sensor inputs and geospatial databases to determine vehicle position. (Image courtesy: University of Central Florida)

---

<https://www.gim-international.com/content/news/ucf-researchers-to-develop-non-gps-location-finder>

---