

Registration Opens for YellowScan LiDAR for Drone 2019 Conference



YellowScan will be hosting its third user conference called 'LiDAR for Drone' from 19-21 March 2019 at the Domaine de Verchant near Montpellier, France. This event is an excellent opportunity to discuss the latest developments of UAV Lidar technologies, share experiences and meet peers that use Lidar. Attendees will

gain insight into the Lidar industry, hear from interesting and innovative users of Lidar and be part of this great ecosystem.

The conference is open to all those interested in Lidar. Pierre d'Hauteville, principal at YellowScan, says his company wants to make it an event that gathers people around the topic of Lidar in an intimate environment where they can get answers to all their questions and concerns.

□ One of the inspiring speakers at the YellowScan 2017 conference.

Speakers, demonstrations and networking

The LiDAR for Drone event has the particularity to be big enough to hear a lot of new stories but small enough to network and make powerful connections within the community. The speakers are the highlight of the event, sharing their stories and providing tools to better use Lidar systems. Field demonstrations are an integral part of the conference as well. In addition to an exciting learning agenda where our speakers are users and technology partners, you will enjoy a great social moment on Wednesday evening in discovering our beautiful home city of Montpellier.

The conference will begin at 5pm on Tuesday 19 March and go on through the afternoon Thursday 21 March. Attendees can get an **early bird ticket** by using the code EARLY20. YellowScan encourages everyone to register as soon as possible as seats are limited.

[Find out more here](#)

[Read the *GIM International* report on the 2017 edition of the event here](#)

□ Field demonstration during the 2017 edition of the YellowScan user conference.

<https://www.gim-international.com/content/news/yellowscan-lidar-for-drone-2019-conference-opens-registration>
